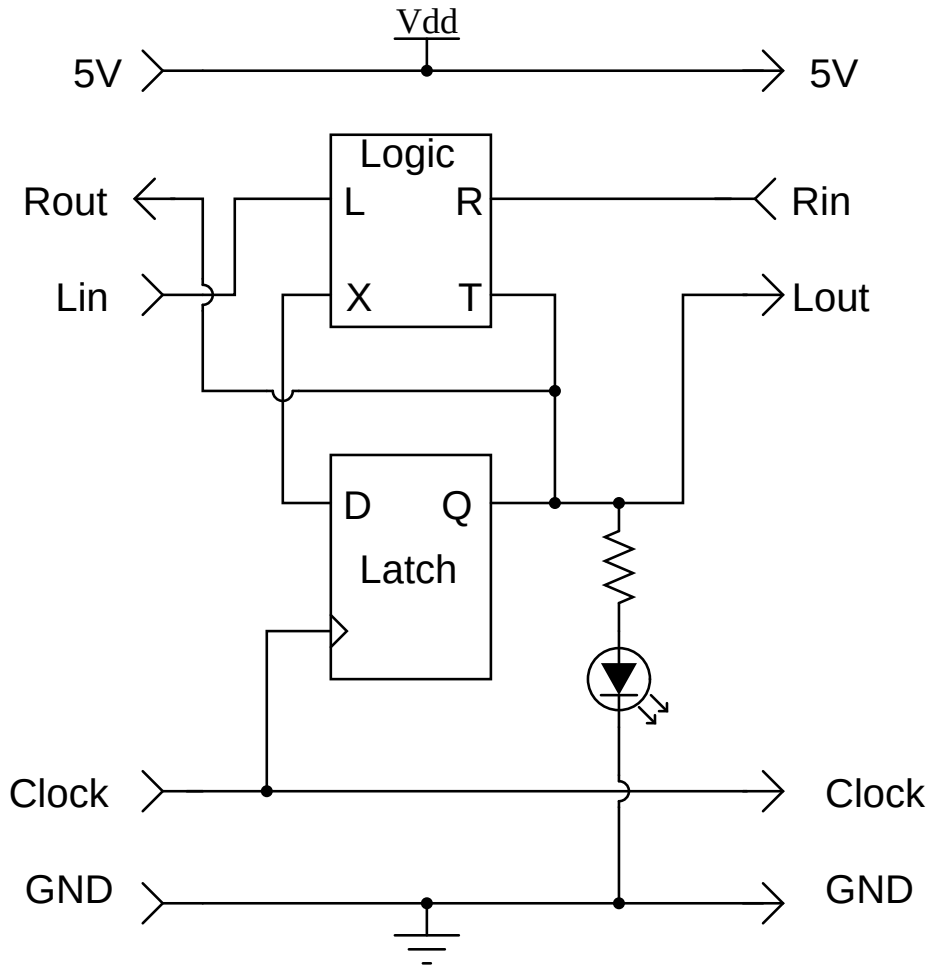

1-d Cellular Automata

X = f(L, T, R)